



# Review of Hand Gesture Recognition Using EMG Signals

<sup>1</sup>Aditi Pandey, <sup>2</sup>Prof. Nitesh Kumar

<sup>1</sup>Research Scholar, <sup>2</sup>Assistant Professor

Department of Electronics & Communication Engineering,  
Sagar Institute of Research & Technology, Bhopal, India

**Abstract—** Hand gesture recognition using electromyography (EMG) signals has gained significant attention in recent years due to its potential applications in human-computer interaction, assistive technologies, and rehabilitation. EMG signals, which capture electrical activity produced by muscle contractions, provide valuable information for detecting and classifying hand movements. Various machine learning and deep learning techniques have been employed to improve the accuracy and efficiency of gesture recognition systems. This review explores the latest advancements in EMG-based hand gesture recognition, highlighting different signal acquisition methods, feature extraction techniques, classification algorithms, and challenges associated with real-time implementation. While promising progress has been made, issues such as signal variability, noise interference, and user dependency remain challenges that require further research. The integration of artificial intelligence and wearable technologies is expected to drive future innovations in this field.

**Keywords—** Hand, Gesture, Recognition, EMG Signals, Machine, Deep learning.

## I. INTRODUCTION

Hand gesture recognition has become an essential area of research due to its wide range of applications in human-computer interaction, prosthetic control, virtual reality, and biomedical engineering. Traditional gesture recognition techniques rely on vision-based approaches, such as camera-based tracking and infrared sensors. While these methods have demonstrated considerable success, they are often limited by environmental conditions, occlusion issues, and privacy concerns [1]. As an alternative, electromyography (EMG)-based gesture recognition has emerged as a promising solution, leveraging muscle activity signals to detect and classify hand movements accurately. EMG sensors measure the electrical activity generated by muscle contractions, offering a reliable and direct method for capturing fine motor movements [2].

EMG-based gesture recognition involves multiple stages, including signal acquisition, preprocessing, feature extraction, and classification. The first step is acquiring EMG signals using surface or intramuscular electrodes. Surface EMG (sEMG) is widely used due to its non-invasive nature and ease of implementation. However, it is prone to noise and requires optimal electrode placement to ensure signal quality. Intramuscular EMG, on the other hand, provides more precise muscle activity data but is invasive and less practical for everyday use. After acquiring raw EMG signals, preprocessing techniques such as filtering, normalization, and noise reduction are applied to enhance signal quality and improve recognition accuracy [3].

Feature extraction plays a crucial role in gesture classification, as it helps in reducing dimensionality and improving computational efficiency. Commonly used features in EMG-based gesture recognition include time-domain features (e.g., mean absolute value, waveform length, root mean square), frequency-domain features (e.g., power spectral density, median frequency), and time-frequency features obtained using wavelet transforms [4]. The extracted features are then used as input for classification models, which range from traditional machine learning algorithms, such as support vector machines (SVM), k-nearest neighbors (KNN), and random forests, to deep learning approaches, including convolutional neural networks (CNNs) and recurrent neural networks (RNNs). Deep learning models have shown superior performance in recent studies due to their ability to learn complex patterns and features directly from raw EMG signals [5].

Despite significant advancements, EMG-based hand gesture recognition faces several challenges. Signal variability across different users, muscle fatigue, electrode displacement, and motion artifacts introduce inconsistencies in gesture classification [6]. Additionally, real-time implementation requires computationally efficient models that can operate on low-power embedded systems or



wearable devices. Addressing these challenges requires the development of adaptive machine learning models, robust signal processing techniques, and optimized hardware solutions [7].

The increasing integration of artificial intelligence (AI) and wearable technology is expected to drive the next generation of EMG-based gesture recognition systems. Emerging research focuses on hybrid models that combine multiple biosignals (e.g., EMG, accelerometer, gyroscope) to improve recognition accuracy and robustness [8]. Furthermore, advancements in edge computing and cloud-based AI are facilitating the deployment of real-time gesture recognition in various applications, such as smart prosthetics, gaming, and assistive communication devices [9]. This review provides a comprehensive analysis of current methodologies, recent advancements, challenges, and future directions in the field of hand gesture recognition using EMG signals.

## II. LITERATURE SURVEY

N. R. et al.,[1] Hand gesture detection, which employs electromyography (EMG) signals, is a dynamic field of research with a diverse array of applications, such as human-machine interfaces and prosthetic devices. For the classification of EMG data, numerous deep-learning algorithms have been developed in recent years. This paper investigates the influence of hybrid models, which combine CNN and RNN models, on the classification of hand gestures using EMG signals.

P. N. Aarotale et al., [2] Electromyographic (EMG) signals are employed in EMG-based hand gesture recognition to analyse the electrical activity produced by muscle contractions in order to interpret and classify hand movements. It has a broad range of applications in the areas of rehabilitation training, prosthesis control, and human-computer interaction. The EMG sensor captures muscle signals by placing electrodes on the skin, which are then processed and filtered to reduce noise.

A. Deb et al.,[3] demonstrates that the DPMAS-Net's accuracy is comparable to the current state-of-the-art results with privacy and exceeds them with non-privacy, despite the presence of privacy-preserving measures (Ninapro DB4 86.4% with privacy and 92.0% without privacy, Biopatrec DB2 89.3%, and the Mendeley Dataset 90.4%). Consequently, the DPMAS-Net model represents a

substantial improvement in the classification of EMG signals for the recognition of hand gestures by integrating differential privacy with deep learning techniques.

P. D. Hile Bustos et al.,[4] This research endeavours to improve the accuracy of motion recognition by utilising deep learning techniques and surface electromyographic (sEMG) signals. We present a convolutional neural network (CNN) model that is specifically engineered to extract and integrate features from multichannel sEMG signals by employing a layering approach to enhance accuracy. Methodology: The proposed model was evaluated by comparing its performance to existing methodologies in a study that included ten amputees who were equipped with prosthetic hands.

W. Cao et al.,[5] This work suggests a novel method for the recognition of stroke patient gestures using deep learning models in order to overcome these obstacles. In order to improve the precise identification of hand movements in stroke patients, we implement a strategy that integrates a denoising autoencoder (DAE), a CNN, and a LSTM.

P. Rani et al.,[6] contrasts the conventional wavelet transform with a tempo-spatial technique that employs the wavelet multiresolution method, utilising eight machine learning algorithms. Two datasets that are publicly accessible are implemented. DB1 is characterised by ideal conditions and a variety of limb positions, whereas DB2 includes dynamic factors such as muscle fatigue and electrode shifting.

H. Shi, et al.,[7] The commercialisation of sEMG-based human-machine interaction (HMI) systems is impeded by the gesture classification model's heavy training burden and weak generalisation performance. In order to surmount these obstacles, eight unsupervised transfer learning (TL) algorithms that were developed on the premise of convolutional neural networks (CNNs) were investigated and contrasted on a dataset that comprised 10 gestures from 35 subjects. CORrelation Alignment (CORAL) achieves a classification accuracy of over 90%, which is 10% higher than methods that do not employ TL.

W. Zhong et al.,[8] Effective control of upper-limb prosthetic appendages necessitates precise hand gesture prediction. The integration of deep networks with high-density surface electromyography (HD-sEMG) arrays has



garnered significant interest due to the high flexibility and multiple degrees of freedom that human hands exhibit. This integration is intended to improve the gesture recognition capabilities. Nevertheless, the specific spatial topology and temporal dependencies present in HD-sEMG data are not thoroughly exploited by many existing methods. Furthermore, these studies frequently have a restricted number of gestures and lack generalisability.

M. Zanghieri et al.,[9] Surface electromyography (sEMG) is a State-of-the-Art (SoA) data source for natural and dexterous control in human-machine interaction for industrial, commercial, and rehabilitation-related applications. The inherent presence of numerous signal variability factors, which impede the generalisation of automated learning models, presents a significant challenge for sEMG-based control, despite its non-invasiveness and versatility. We present an unsupervised adaptation technique for sEMG classification in this work and apply it to the variability of arm posture.

S. Song et al.,[10] The surface electromyography (sEMG) signal is a physiological electrical signal that is generated by muscle contraction. The characteristics of the sEMG signal can be used to effectively identify various gestures. Because of their capacity to acquire spatial features of sEMG signals, convolutional neural networks (CNNs) are currently extensively employed in sEMG gesture recognition systems. Nevertheless, these classical CNNs are ineffective in deriving the temporal correlation that is present in the time serials of sEMG signals, a factor that is undoubtedly significant for gesture recognition.

### III. CHALLENGES

Despite the significant advancements in hand gesture recognition using electromyography (EMG) signals, several challenges remain that hinder the development of robust, accurate, and user-independent systems.

**Signal Variability and Individual Differences-** One of the major challenges in EMG-based gesture recognition is the variability of EMG signals among different users. Factors such as muscle composition, skin impedance, and electrode placement significantly impact signal quality and consistency. This variability makes it difficult to develop a generalized model that performs accurately across diverse populations.

**Noise and Artifacts in EMG Signals-** EMG signals are highly susceptible to noise and artifacts caused by external factors such as power line interference, motion artifacts, and electrode displacement. These unwanted disturbances can degrade signal quality and reduce the accuracy of gesture recognition systems. Effective signal preprocessing and noise reduction techniques are essential to mitigate these issues.

**Electrode Placement and Skin Contact-** The accuracy of EMG-based gesture recognition is heavily dependent on electrode placement and skin contact. Variations in electrode positioning can lead to inconsistent signal acquisition, making it difficult to reproduce the same results across different sessions. Ensuring proper electrode placement and maintaining stable skin contact is crucial for reliable gesture recognition.

**Real-Time Processing and Computational Constraints-** Implementing real-time EMG-based gesture recognition requires fast and efficient processing of large amounts of data. Many machine learning and deep learning models are computationally intensive, making them unsuitable for low-power embedded systems and wearable devices. Optimizing algorithms for real-time performance while maintaining accuracy is a key challenge in this field.

**Muscle Fatigue and Gesture Repeatability-** Muscle fatigue can alter the amplitude and frequency characteristics of EMG signals, affecting the accuracy of gesture classification over extended periods. Users may experience changes in muscle activation patterns, leading to inconsistencies in gesture recognition. Developing adaptive models that can compensate for muscle fatigue is necessary for long-term usability.

**Limited Training Data and Model Generalization-** The performance of machine learning models depends on the availability of large, diverse, and high-quality training datasets. However, collecting and labeling EMG data for different hand gestures is time-consuming and labor-intensive. Additionally, models trained on a specific dataset may struggle to generalize to new users or environments, necessitating transfer learning or personalized calibration techniques.

**Integration with Wearable and Assistive Devices-** EMG-based gesture recognition is often implemented in wearable devices such as prosthetic hands, smart gloves, and rehabilitation systems. Ensuring seamless integration of



recognition algorithms with hardware components while maintaining user comfort and device portability poses significant design challenges.

#### IV. CONCLUSION

Hand gesture recognition using EMG signals has emerged as a promising technology for applications in human-computer interaction, assistive devices, and rehabilitation systems. While significant advancements have been made in signal processing, feature extraction, and classification techniques, challenges such as signal variability, noise interference, electrode placement sensitivity, and real-time computational constraints still hinder widespread adoption. The integration of artificial intelligence, deep learning, and wearable technology is expected to enhance accuracy and robustness, paving the way for more intuitive and reliable gesture recognition systems. Future research should focus on developing adaptive models, improving real-time performance, and addressing ethical concerns to ensure practical implementation in medical, industrial, and consumer applications.

#### REFERENCES

1. N. R and G. Titus, "Hybrid Deep Learning Models for Hand Gesture Recognition with EMG Signals," 2024 International Conference on Advances in Modern Age Technologies for Health and Engineering Science (AMATHE), Shivamogga, India, 2024, pp. 1-6, doi: 10.1109/AMATHE61652.2024.10582166.
2. P. N. Aarotale and A. Rattani, "Machine Learning-based sEMG Signal Classification for Hand Gesture Recognition," 2024 IEEE International Conference on Bioinformatics and Biomedicine (BIBM), Lisbon, Portugal, 2024, pp. 6319-6326, doi: 10.1109/BIBM62325.2024.10822133.
3. A. Deb, R. Roy, M. S. Sadik Rian, A. Islam and C. Shahnaz, "DPMAS-Net: A Privacy-Preserving Deep Learning Model for EMG-Based Hand Gesture Recognition with Time-Frequency Domain Features," 2024 IEEE Region 10 Symposium (TENSYP), New Delhi, India, 2024, pp. 1-6, doi: 10.1109/TENSYP61132.2024.10752112.
4. P. D. Hile Bustos, R. R. Serrezuela, A. A. Suarez Leon, A. E. Rivera Gomez and D. M. Echeverry Suaza, "Electromyographic EMG signal recognition of hand gestures for multi-class prostheses based on DWT and CNN," 2024 IEEE VII Congreso Internacional en Inteligencia Ambiental, Ingeniería de Software y Salud Electrónica y Móvil (AmITIC), David, Panama, 2024, pp. 1-7, doi: 10.1109/AmITIC62658.2024.10747601.
5. W. Cao et al., "EMG Based Rehabilitation Gesture Recognition Using DAE-CNN-LSTM Hybrid Model," 2024 World Rehabilitation Robot Convention (WRRC), Shanghai, China, 2024, pp. 1-6, doi: 10.1109/WRRC62201.2024.10696763.
6. P. Rani, S. Pancholi, V. Shaw, M. Atzori and S. Kumar, "Enhanced EMG-Based Hand Gesture Classification in Real-World Scenarios: Mitigating Dynamic Factors With Tempo-Spatial Wavelet Transform and Deep Learning," in IEEE Transactions on Medical Robotics and Bionics, vol. 6, no. 3, pp. 1202-1211, Aug. 2024, doi: 10.1109/TMRB.2024.3408896.
7. H. Shi, X. Jiang, C. Dai and W. Chen, "EMG-based Multi-User Hand Gesture Classification via Unsupervised Transfer Learning Using Unknown Calibration Gestures," in IEEE Transactions on Neural Systems and Rehabilitation Engineering, vol. 32, pp. 1119-1131, 2024, doi: 10.1109/TNSRE.2024.3372002.
8. W. Zhong, Y. Zhang, P. Fu, W. Xiong and M. Zhang, "A Spatio-Temporal Graph Convolutional Network for Gesture Recognition from High-Density Electromyography," 2023 29th International Conference on Mechatronics and Machine Vision in Practice (M2VIP), Queenstown, New Zealand, 2023, pp. 1-6, doi: 10.1109/M2VIP58386.2023.10413402.
9. M. Zanghieri, M. Orlandi, E. Donati, E. Gruppioni, L. Benini and S. Benatti, "Online Unsupervised Arm Posture Adaptation for sEMG-based Gesture Recognition on a Parallel Ultra-Low-Power Microcontroller," 2023 IEEE Biomedical Circuits and Systems Conference (BioCAS), Toronto, ON, Canada, 2023, pp. 1-5, doi: 10.1109/BioCAS58349.2023.10388902.
10. S. Song, A. Dong, J. Yu, Y. Han and Y. Zhou, "A Multichannel CNN-GRU Hybrid Architecture for sEMG Gesture Recognition," 2023 IEEE International Conference on Bioinformatics and Biomedicine (BIBM), Istanbul, Turkiye, 2023, pp. 4132-4139, doi: 10.1109/BIBM58861.2023.10385891.